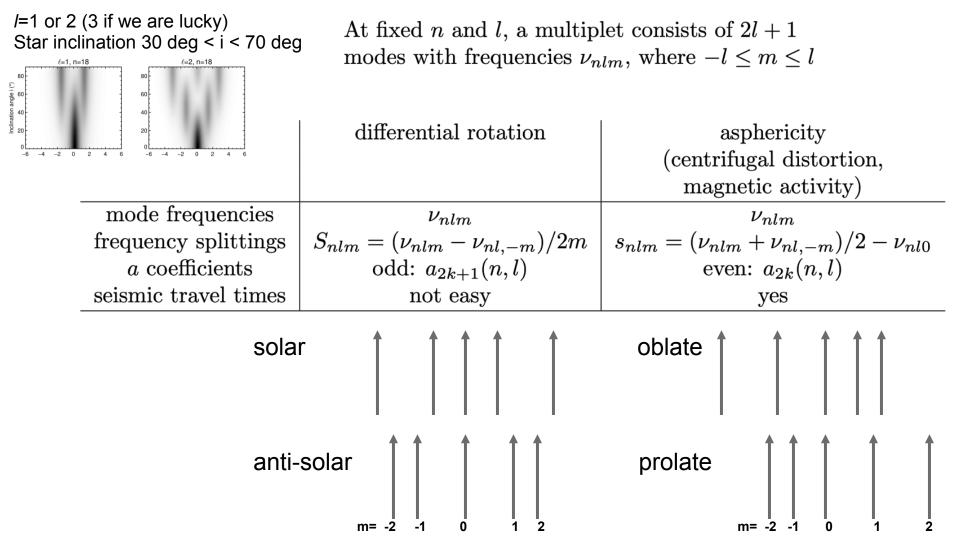
# Asteroseismic measurements of stellar differential rotation and asphericity

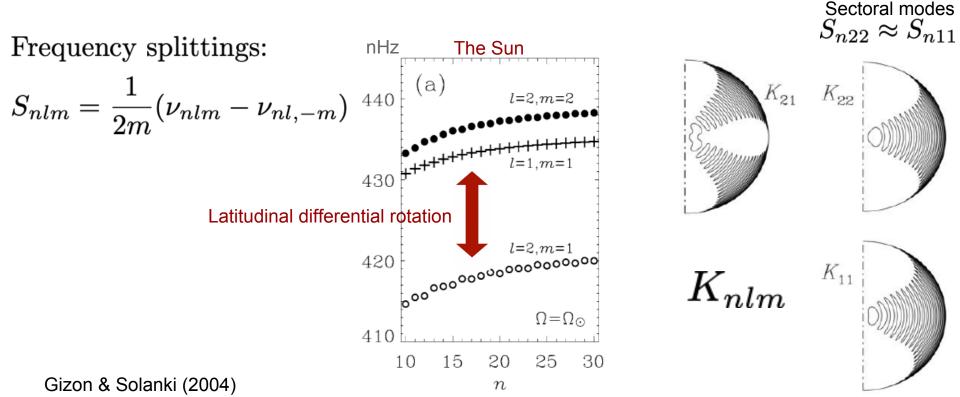
- Observables: frequency splittings, *a*-coefficients, seismic travel times
- Differential rotation
- Asphericities
- Unsteady perturbations, e.g. due to a single active region

Laurent Gizon Max Planck Institute for Solar System Research



Mode frequencies (weak rotation):

 $\nu_{nlm} = \nu_{nl} + m \iint K_{nl|m|}(r,\theta)\Omega(r,\theta) \ rdrd\theta + \text{centrifugal term}(|m|)$ 



a-coefficients 
$$v_{nlm} = v_{ln} + \sum_{j=1}^{2l+1} a_j(n,l) \mathcal{P}_j^{(l)}(m).$$

The  $\mathcal{P}_{j}^{(l)}(m)$  are polynomials of degree j that are uniquely determined by the orthogonality condition  $\sum_{m} \mathcal{P}_{j}^{(l)}(m) \mathcal{P}_{k}^{(l)}(m) = 0$  for  $j \neq k$ , and the normalization  $\mathcal{P}_{j}^{(l)}(l) = l$  (Ritzwoller & Lavely 1991; Schou, JCD, Thompson 1994). The frequency perturbations due to the linear effect of rotation are encoded in the odd coefficients,

$$S_{n11} = a_1(1, n),$$
  
 $S_{n2m} = a_1(2, n) + \frac{1}{3}(5m^2 - 17)a_3(2, n)$ 

Ritzwoller & Lavely (1991) showed that the inversion of the a-coefficients is made easy by parametrizing the angular velocity as follows:

$$\Omega(r,\theta) = \Omega_0(r) + \sum_{j=1} \Omega_j(r) W_j(\theta),$$

where  $W_j(\theta) = P_{2j+1}^1(\cos\theta) / \sin\theta$ . This decomposition is used routinely in helioseismology. The first two terms are

$$W_1(\theta) = \frac{3}{2} (5\cos^2 \theta - 1)$$
$$W_2(\theta) = \frac{15}{8} (21\cos^4 \theta - 14\cos^2 \theta + 1)$$

The advantage of this expansion is that each  $\Omega_j(r)$  can be determined from the coefficients  $a_{2j+1}(n,l)$  alone.

In practice, with disk-integrated data, it is too ambitious to want to measure all coefficients  $a_1(1, n)$ ,  $a_1(2, n)$ , and  $a_3(2, n)$ . Instead we may fit two parameters:

 $a_1 := a_1(1, n)$  $a_3 := a_3(2, n)$ 

The additional constraint  $S_{n11} = S_{n22}$  prompts us to parametrize the frequencies as follows:

Recommended parametrization of rotational splitting for sun-like stars

$$\nu_{n1m} = \nu_{n1} + m(a_1 + a_3) + \text{asphericity term}$$

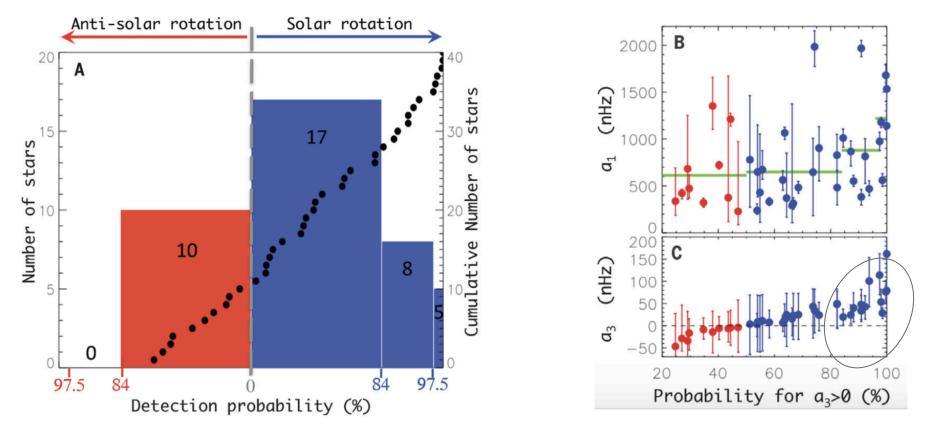
$$\nu_{n2m} = \nu_{n2} + ma_1 + \frac{1}{3}(5m^3 - 17m)a_3 + \text{asphericity term}$$
Gizon & Solanki (2004)

With only two independent parameters we can constrain models of the form

$$\Omega(r,\theta) = \begin{cases} \Omega_0 + \Omega_1 W_1(\theta) & r_c \le r \le R\\ \Omega_0 & 0 \le r < r_c \end{cases}$$

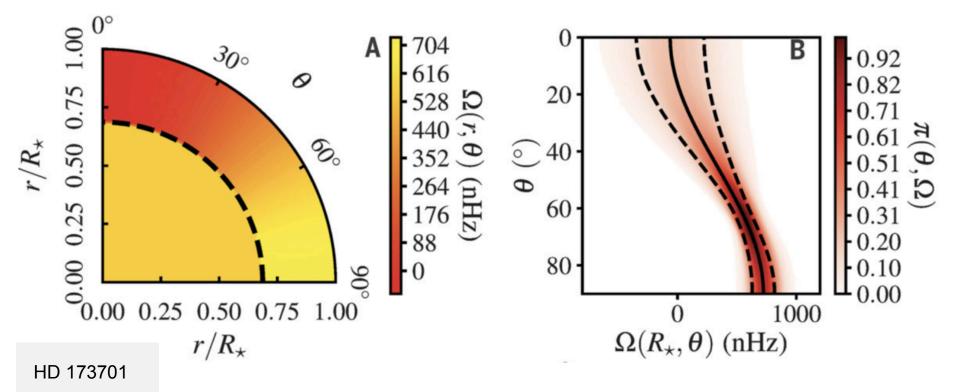
assuming we have an estimate of the depth of the convection zone,  $r_c$ . The inversion is trivial, there is a one-to-one relationship between  $\Omega_0$  and  $a_1$  and between  $\Omega_1$  and  $a_3$  (see Gizon & Solanki 2004).

#### Differential rotation: a3-coefficients --- Sun-like stars



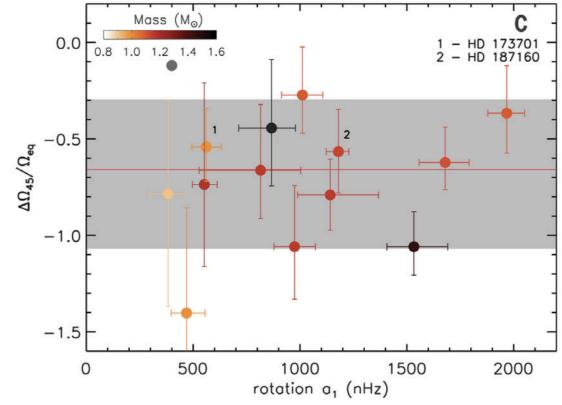
Benomar et al. (2018), following Gizon & Solanki (2004) parametrization

Differential rotation: a3-coefficients --- Sun-like stars



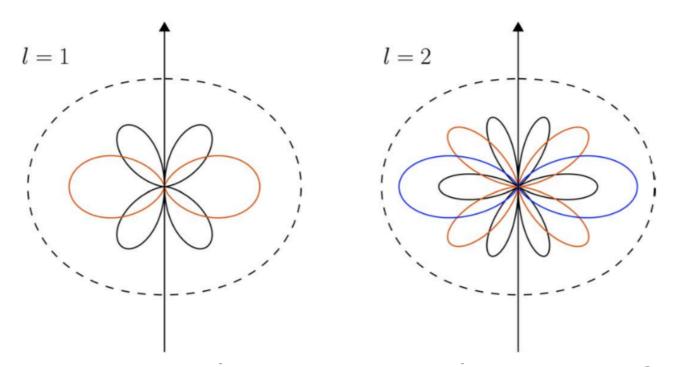
Benomar et al. (2018)

#### Differential rotation: a3-coefficients --- Sun-like stars



Benomar et al. (2018)

Measurements of stellar asphericity



Polar plots of the kinetic energy density  $E_{lm}(\theta) = c_{lm} \left[P_l^m(\cos\theta)\right]^2 \sin\theta$ ,

Gizon et al. (2017)

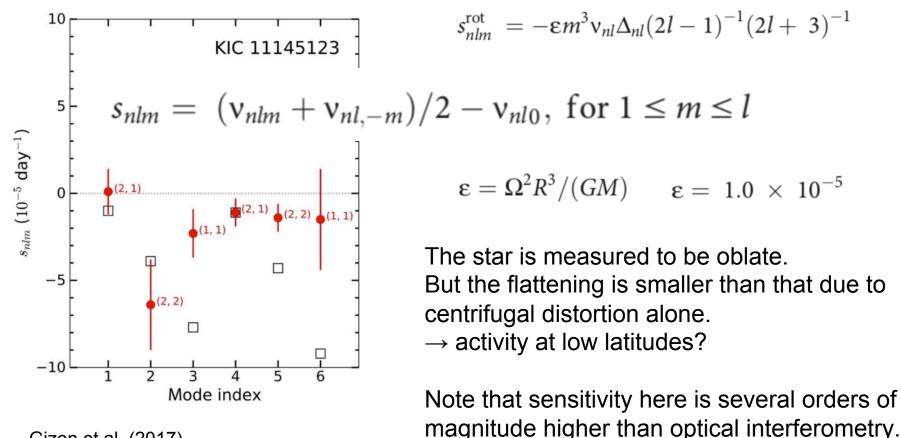
Stellar asphericity: centrifugal distortion

$$v_{nlm} \approx v_{nl} + m\Omega/(2\pi) + \varepsilon v_{nl}\Delta_{ln}Q_{2lm}$$

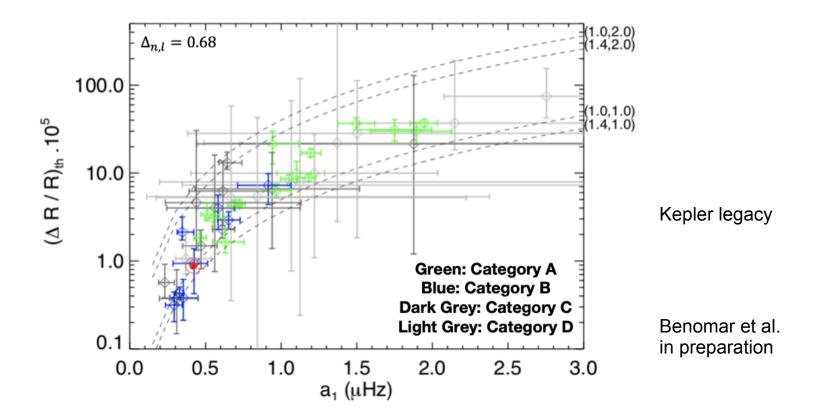
The effect is proportional to the ratio of the centrifugal to the gravitational forces  $\epsilon = \Omega^2 R^3 / (GM)$ 

$$Q_{2lm} = \int_0^{\pi} d\theta \ P_2(\cos\theta) E_{lm}(\theta) = [l(l+1) - 3m^2](2l-1)^{-1}(2l+3)^{-1}$$
$$\Delta_{nl} = 4/3 \int_0^R dr (r/R)^3 \xi_{nl}^2(r) \rho r^2$$

#### Example: long lived acoustic oscillations



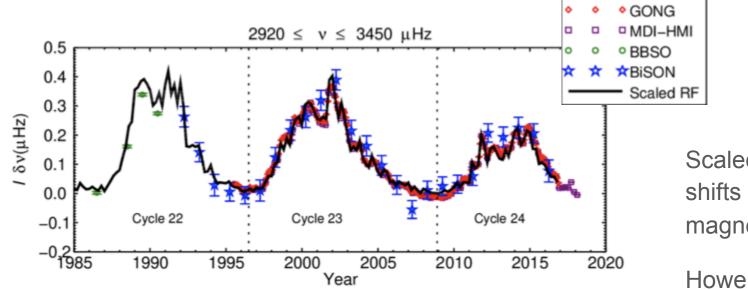
Gizon et al. (2017)





### Stellar asphericity: magnetic activity

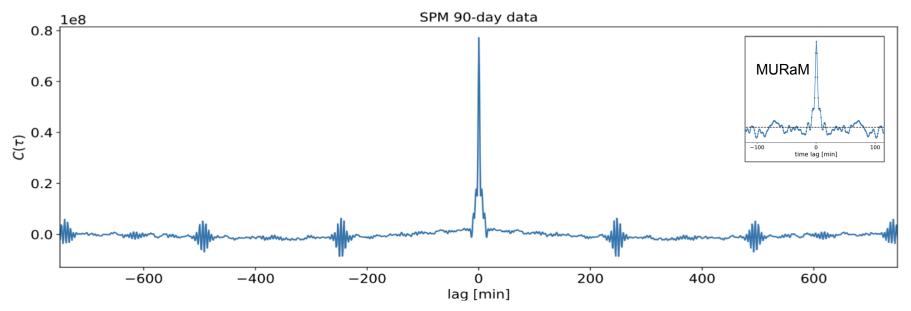
Surface magnetic activity  $\rightarrow$  local increase in wave speed.

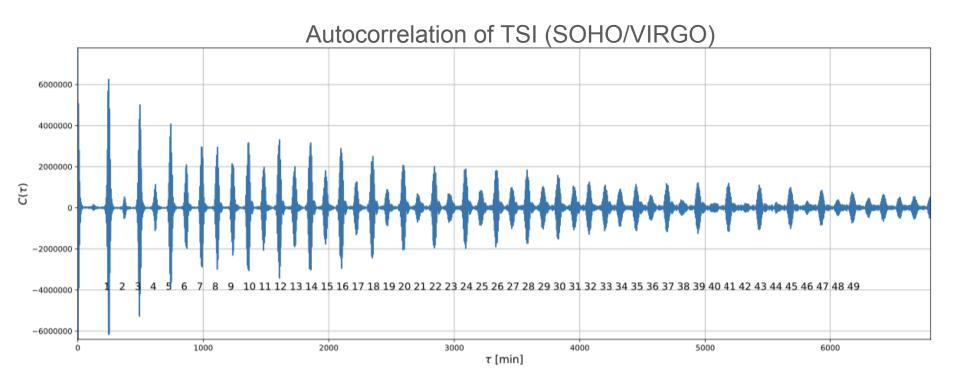


Scaled frequency shifts due to surface magnetic activity

Howe et al. 2018

#### Autocorrelation of TSI (SOHO/VIRGO)





The measurement and interpretation of travel times is well understood in local helioseismology. See Gizon & Birch (2002, 2004) and Fournier et al. (2014).

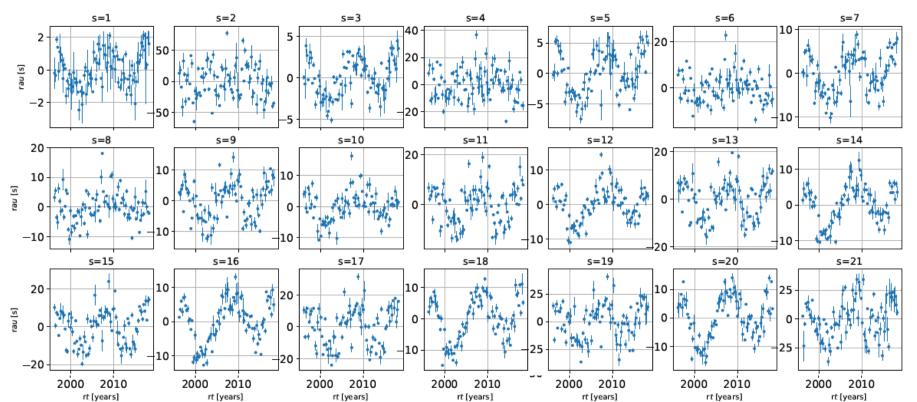
$$C(t) = \int_0^T I(t')I(t'+t)dt'$$
  

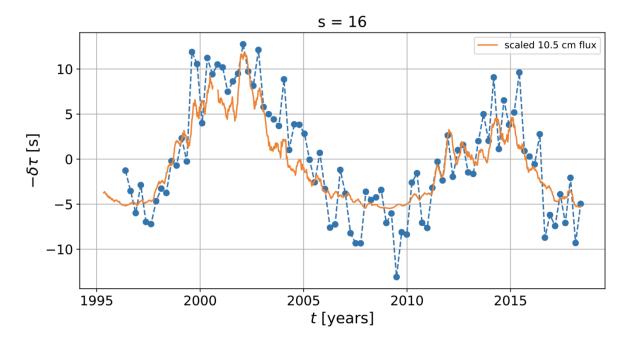
$$\delta\tau_s = \int W_s(t)[C(t) - C_{\rm ref}(t)]dt$$
  

$$W_s(t) = -\frac{f_s(t)dC_{\rm ref}/dt}{\int dt' f_s(t')[dC_{\rm ref}/dt']^2 dt'}$$

where  $f_s(t)$  selects a window around the arrival time for skip s.

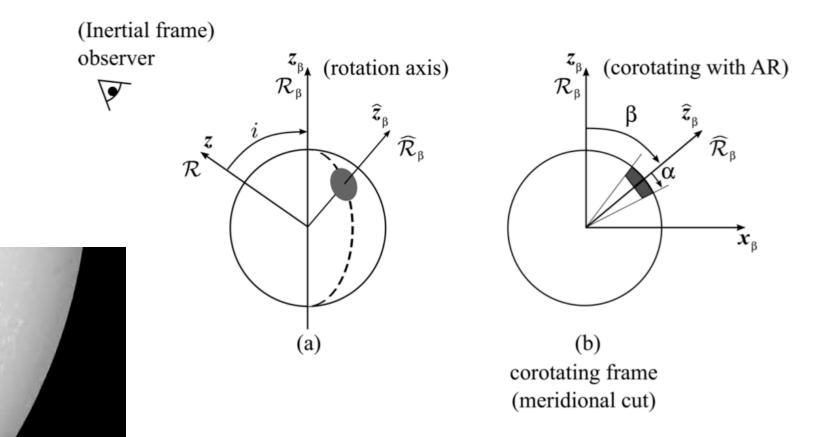
Solar-cycle dependence of travel times

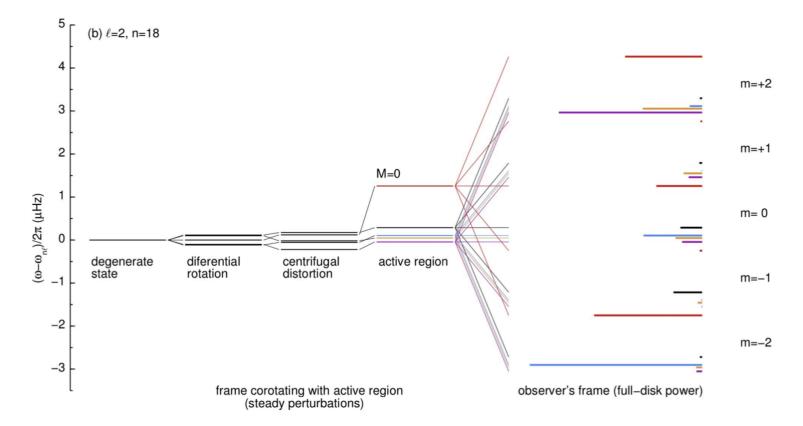


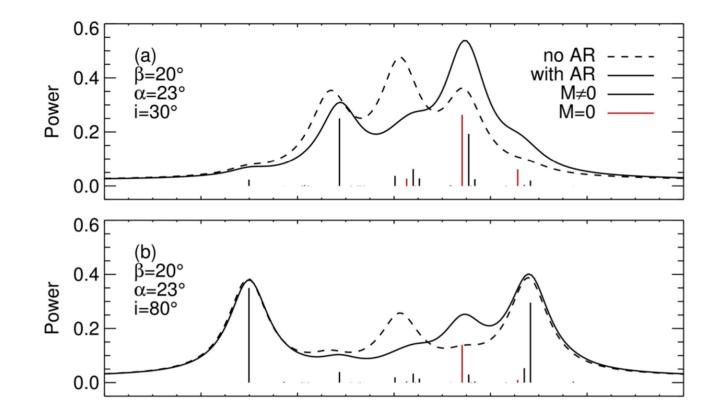


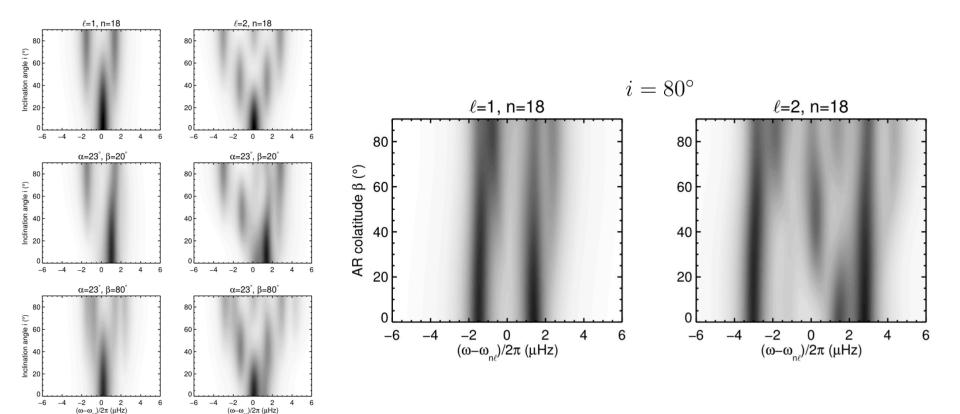
Multiple-skip travel times, taken all together, contain information about the butterfly diagram.

→ Apply methods of *local helioseismology* 









## Summary

- The effects of stellar latitudinal differential rotation, rotational flattening, magnetic activity are measurable in the acoustic spectra of sun-like stars (*i*>45 deg).
- Based on knowledge from helioseismology, the proper way to measure these effects is to fit *a*-coefficients, not individual mode frequencies. (The *a*-coefficients cannot easily be computed from fitted azimuthal frequencies.)
- PLATO development: No need to worry about this immediately, but it may need to be included at some point in the future.
- Warning: It is not ruled out that some p-mode spectra will prove to be very difficult to interpret (cf. unsteady perturbations).